



Adaptation of real-time scheduler RUN to Mixed-Criticality Systems

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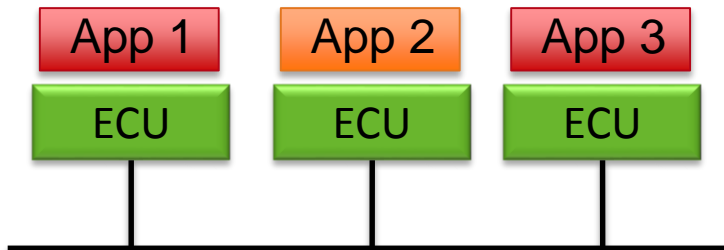
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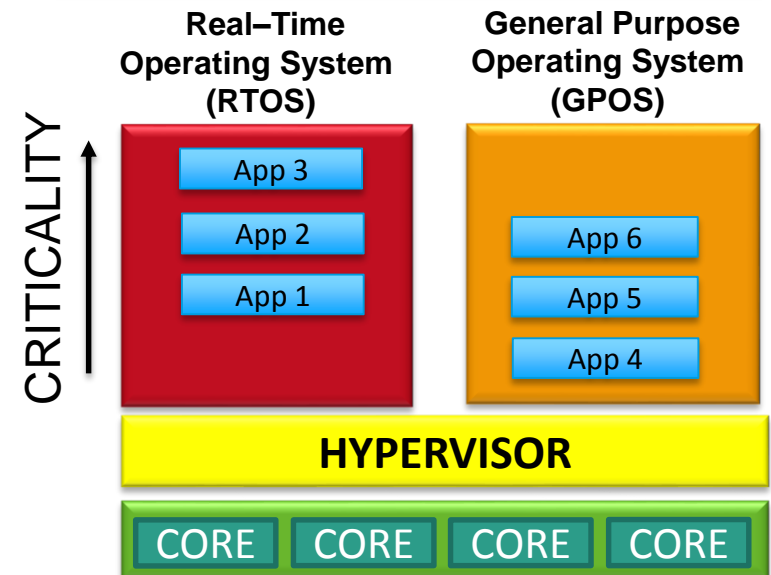
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Current Architecture: Federated Architecture



Considered Architecture: Integrated Architecture



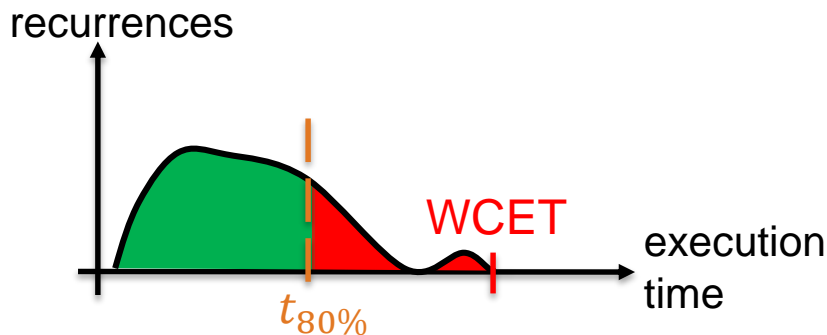
SO HOW TO PROPERLY SCHEDULE ALL THESE APPLICATIONS ?

- ◆ Each application is modelled as a set of tasks, more precisely Real-Time tasks
- ◆ Each Real-Time task T_i follows the Periodic Task model:
 - ◆ Period/Deadline P_i (implicit deadline)
 - ◆ Worst Case Execution Time (WCET) C_i
 - ◆ Utilization $U_i = \frac{C_i}{P_i}$
- ◆ Refined problem : deploying these applications on a multicore platform = problem of preemptively scheduling real-time tasks on a multicore platform

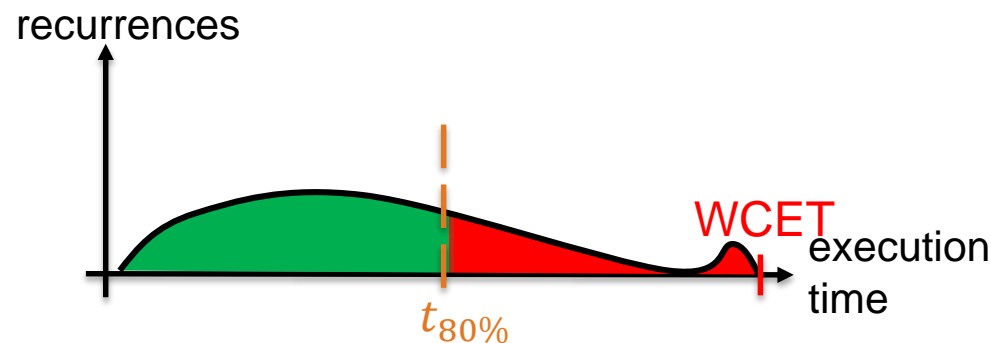
- ◆ Task set has to pass a schedulability test based on utilization bound :

$$U_{set} = \sum U_i \leq L(M, A)$$

- ◆ Complexity of multi-core architecture has changed the way WCET are assessed :



UNIPROCESSOR



MULTI-PROCESSOR

- ◆ **Implicit hypothesis: all tasks are paramount to system dependability**
 - ◆ Use of WCETs unavoidable
 - ◆ Poor effective utilization of the platform

- ◆ **Concepts and definitions behind Mixed-criticality**
- ◆ **Presentation of RUN principles**
- ◆ **Adaptation of RUN to Mixed-Criticality**

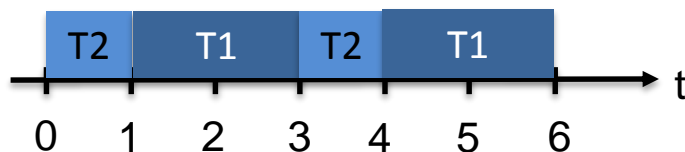
Consider that some tasks can be sacrificed (stopped):

- ◆ Classify tasks into two “criticality levels”
Lo (not paramount) and Hi (paramount)
- ◆ The scheduler allocates a CPU time budget B_i to each task T_i
- ◆ Monitor execution times to enforce two execution modes :
 - ◆ Full mode (F-mode) :
 - ◆ Execute all tasks
Remark: In most cases, tasks completed consuming less than B_i
 - ◆ Set B_i to an optimistic time bound (e.g. $t_{80\%}$)
 - ◆ Safe mode (S-mode):
 - ◆ Execute only Hi-criticality tasks
 - ◆ $B_i = C_i$ **required**
- ◆ Task scheduling starts in F-mode and switch to S-mode
as soon as required...

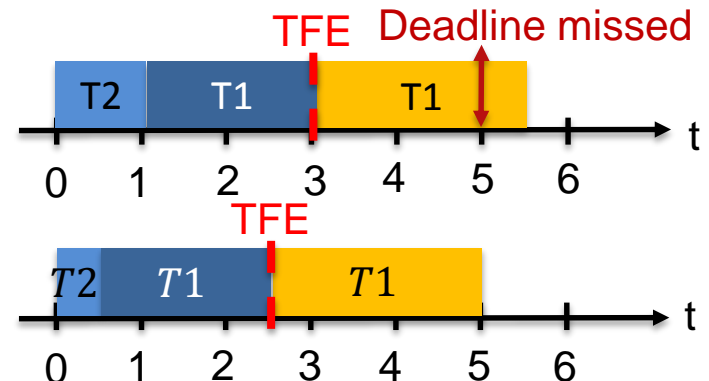
- ◆ **Timing Failure Event (TFE): a task depleted its budget without completing**
- ◆ **TFE triggers a Mode Change :**
 - ◆ Lo-criticality tasks are discarded
 - ◆ Use of the S-mode timing parameters

Task	Period	Criticality	B_{F-mode}	B_{S-mode}
T1	5	Hi	2 ($U_1=0,4$)	4,5 ($U_1=0,9$)
T2	3	Lo	1 ($U_2=0,33$)	1 ($U_2=0,33$)

Execution without Mode Change



Execution with Mode Change

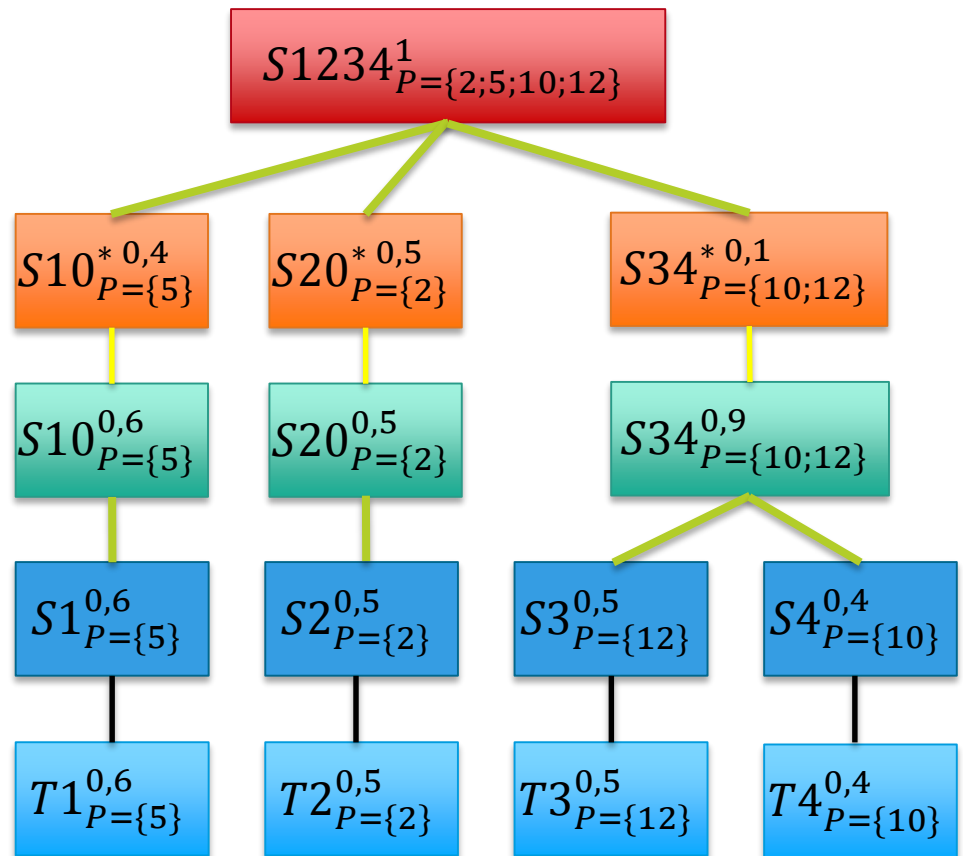


- ◆ **RUN aims at transforming a multiprocessor scheduling problem into multiple uniprocessor ones:**
 - ◆ Scheduling based on a hierarchy of servers
 - ◆ Two kinds of servers:
 - ◆ Primal Server: schedule other servers with EDF scheduling policy
 - ◆ Dual Server: corresponds to idle time of primal server
 - ◆ The hierarchy is generated **offline**...
 - ◆ ... and is used **online** to take the scheduling decisions
- ◆ **For each task set RUN will use the least number of processors necessary for its proper scheduling**

Generation of the hierarchy of servers

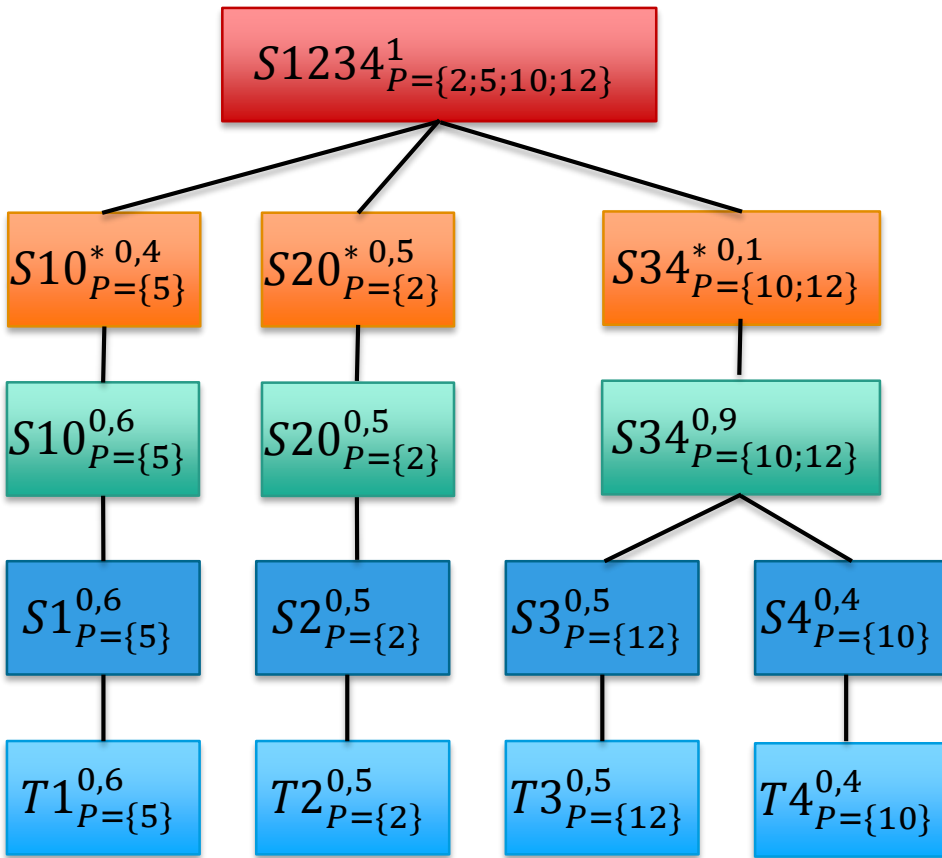
Task	Period	Utilization
T1	5	0,6
T2	2	0,5
T3	12	0,5
T4	10	0,4

Number of processors required: 2

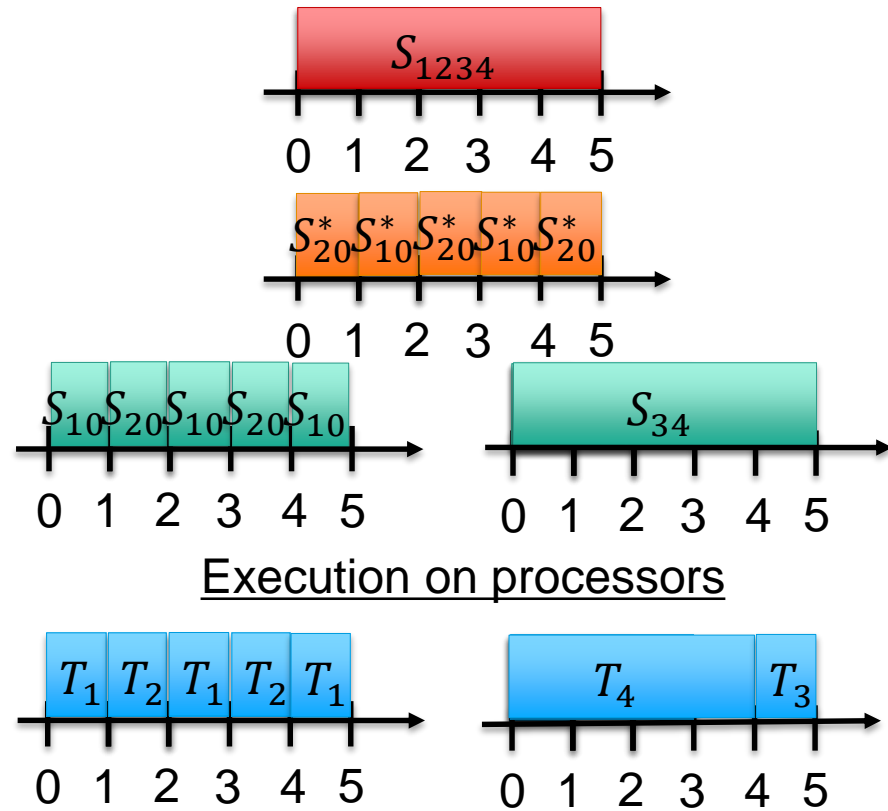


— Packing operation

— Dual operation



Intermediate virtual scheduling operations



➔ Objective:

Reduce the required number of processors to schedule a task set compared to non-modified RUN

- ◆ **First ensure the proper scheduling of the S-mode**
- ◆ **Enable Lo tasks when Hi tasks complete early:**
 - ◆ Split Hi-criticality task budgets into two => *start* and *finish* tasks
 - start* budget B_i^{F-mode}
 - finish* budget $B_i^{S-mode} - B_i^{F-mode}$
 - ◆ Re-allocate finish budget to schedule Lo task in F-mode
- ➔ **Introduce Modal Servers into RUN hierarchy of servers**
- ◆ **Create another RUN schedule for remaining Lo tasks**

- ◆ **Modal server = execution server with a periodically-replenished budget**
 - ◆ Schedule a set of Lo tasks in F-mode
 - ◆ Schedule one Hi-criticality task (*finish* task)
- ◆ **Two schedulability tests for Lo task scheduling**
 - ◆ When all task periods are a multiple of Modal Server period Modal Server utilization = schedulability bound
 - ◆ Otherwise, MS is less effective and provides a fewer amount of utilization to Lo tasks
- ◆ **How to assign Lo tasks to Modal Servers based on its utilization ?**
- ◆ **Allocation problem has been transformed into an accessibility problem**

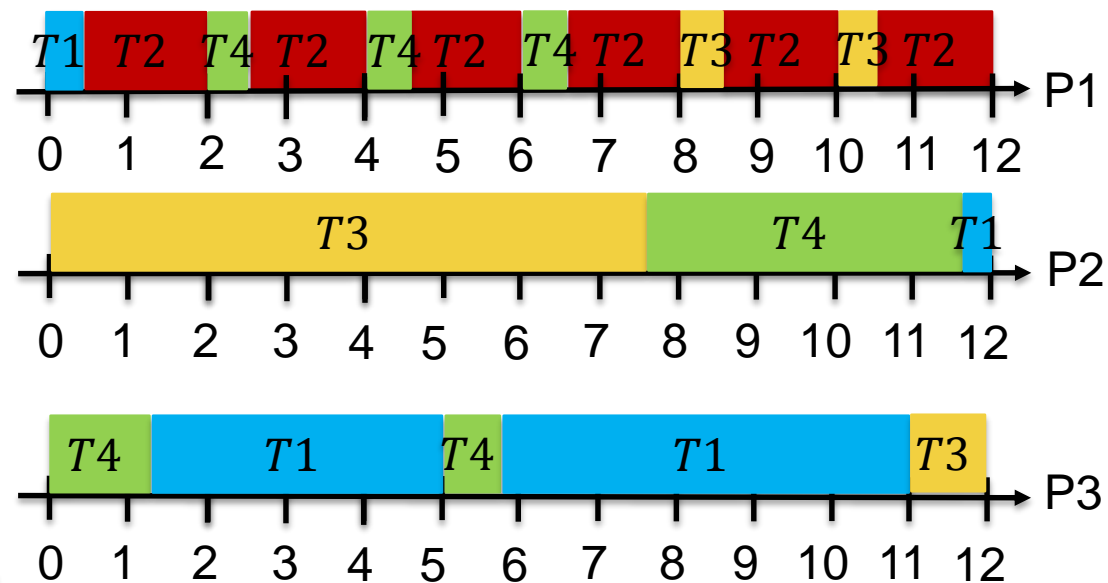
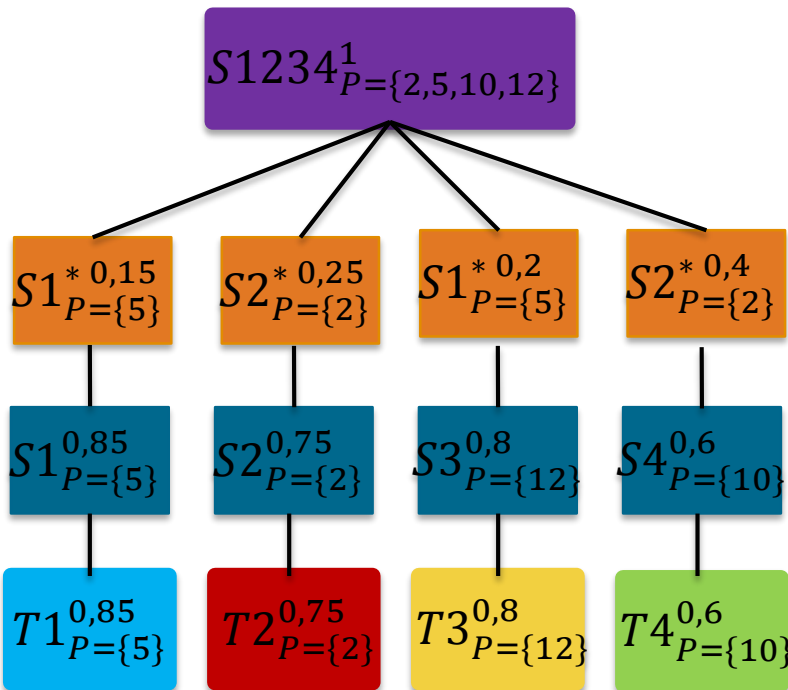
Task	Period	Criticality	Utilization (F-mode)	Utilization (S-mode)
T1	5	Hi	0,6	0,85
T2	2	Hi	0,5	0,75
T3	12	Hi	0,5	0,8
T4	10	Hi	0,4	0,6
T5	8	Lo	0,25	0
T6	15	Lo	0,25	0
T7	3	Lo	0,5	0
T8	20	Lo	0,125	0

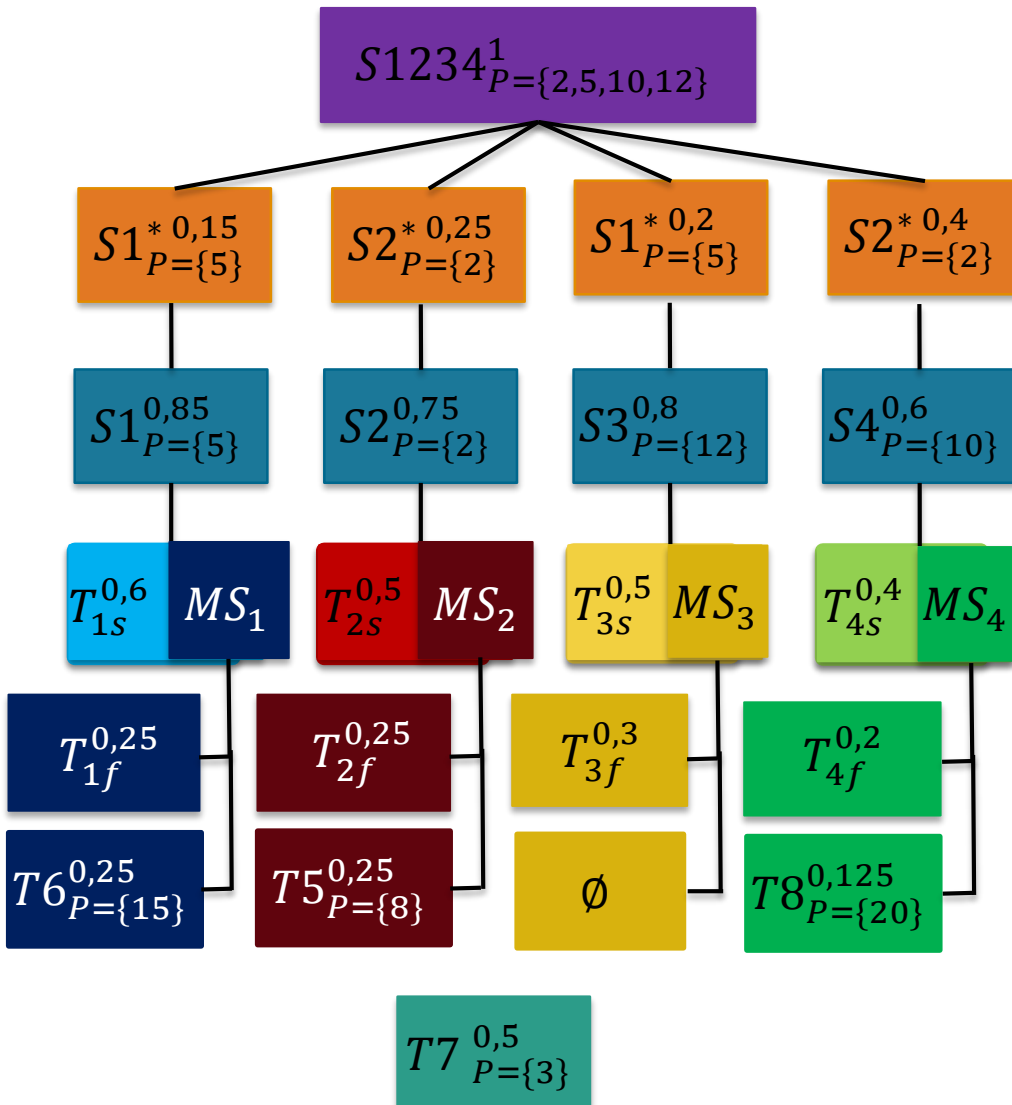
- ◆ **Scheduling Lo/F-mode+Hi/S-mode tasks RUN needs 5 processors**
- ◆ **Scheduling F-mode needs 4 processors**
- ◆ **Scheduling S-mode needs 3 processors**
- ◆ **Objective: schedule this system with fewer than 5 processors**

- ◆ Generate the hierarchy of servers for Hi tasks only

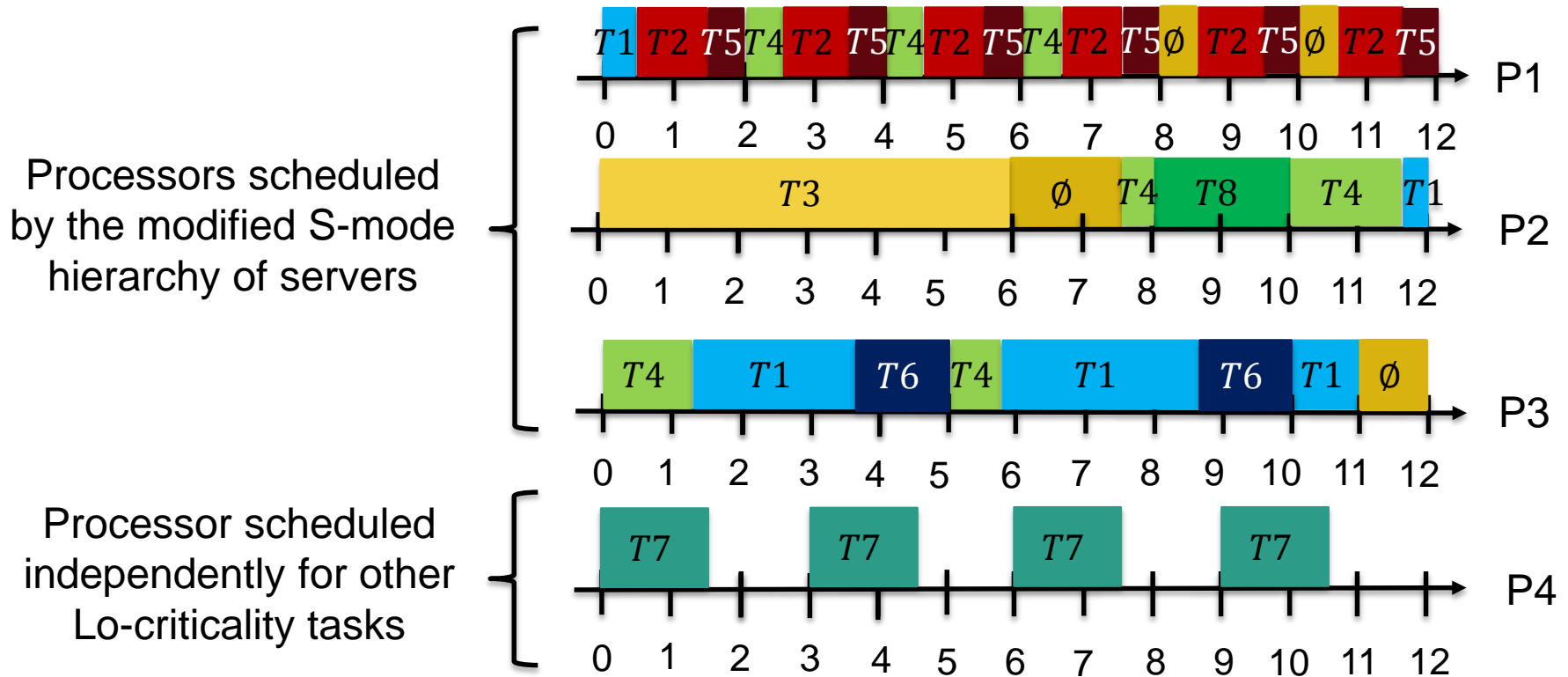
Offline

Online





- ◆ Start from S-mode hierarchy of servers
- ◆ Separate Hi tasks into 2 parts
- ◆ Allocate Lo tasks to Modal Servers
- ◆ Schedule independently remaining Lo tasks



Set of Tasks / Mode	Ceiling utilization
All/S-mode	5
Lo/F-mode	2
Hi/S-mode	3
Adapted RUN	4

- ◆ **Our adaptation requires fewer processors to schedule this task set**
- ◆ **Lo task allocation done with Uppaal**
- ◆ **Better result than fpEDF-VD requires : 8 processors**

- ◆ **1st adaptation of RUN to Mixed-Criticality systems**
- ◆ **Optimality is lost**
- ◆ **Mode changes correctly handled**
- ◆ **Fewer processors requires for scheduling task set**
- ◆ **Use of Uppaal for Lo task allocation**
- ◆ **Future works:**
 - ◆ Extensive experiments to be conducted

Any questions ?