

# The Complexity of Concurrent Rational Synthesis

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*Theorem*

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*The synthesis problem for LTL is 2EXPTIME complete.*



## The Rational Synthesis

$A_0 \uplus A_1 \uplus \dots \uplus A_n$  sets of actions,  $\varphi_0$  LTL formula.

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$\vdots$

$P_n :$

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$\rho$  is **good** if  $\rho \models \varphi_0$  or  $\rho \not\models \varphi_0$  and  $(\sigma_0, \dots, \sigma_n)$  is not a *rational behavior*

# Nash Equilibria

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Nash equilibrium is a profile  $\sigma$  such that:

$$\forall i \in N, \forall \tau \in \Sigma_i, \text{Payoff}_i((\tau, \sigma_{-i})) \leq \text{Payoff}_i(\sigma) .$$

- $N$  is the set of players.
- $\Sigma_i$  is the set of possible strategies for player  $i$ .



## 0-fixed Nash Equilibria

### Definition

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0 – NE is a profile  $(\sigma_0, \sigma_{-0})$  such that:

$$\forall i \in N \setminus \{0\}, \forall \tau \in \Sigma_i ,$$
$$\text{Payoff}_i((\sigma_0, \sigma_{-0})) \geq \text{Payoff}_i((\sigma_0, \sigma_{-(0,i)}, \tau)) .$$

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## The Rational Synthesis

$A_0 \uplus A_1 \uplus \dots \uplus A_n$  sets of AP,  $\varphi_0, \varphi_1, \dots, \varphi_n$  LTL formulas.

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*Theorem (KPV 14)*

*The rational synthesis problem for LTL is 2EXPTIME complete.*

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The original proof

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The following SL formula:

$$\psi \equiv \bigwedge_{i=1}^k \llbracket \tau_i \rrbracket (b(\sigma_{-i}, \tau_i)(\varphi_i \rightarrow b(\sigma)\varphi_i))$$

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Alternative approach

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Provide a direct game theoretic proof.

# Formal setting

## The game graph

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Let  $\mathcal{G} = (\text{St}, s_0, \mathbf{N}, (\text{Act}_i)_{i \in \mathbf{N}}, \text{Tab})$  be a concurrent game structure, Where :

- $\text{St}$  is the set of states in the game,
- $s_0$  is the initial state,
- $\mathbf{N} = \{0, 1, \dots, n\}$  is the set of players,
- $\text{Act}_i$  is the set of actions of Player,
- $\text{Tab} : \text{St} \times \prod_{i \in \mathbf{N}} \text{Act}_i \rightarrow \text{St}$  is the transition table.



# Strategies and payoffs

## Strategies

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A *strategy* for Player  $i$  is a mapping :

$$\sigma_i : \text{St} \left( \prod_{i \in N} \text{Act}_i \text{ St} \right)^* \rightarrow \text{Act}_i .$$

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## Payoffs

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Given a profile  $\sigma$ ,

$$\text{Payoff}_i(\sigma) = 1 \text{ if } \rho \models \varphi_i$$

where  $\rho$  is the play induced by  $\sigma$ .

# Non Cooperative Rational Setting

NCRS Problem

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Is there a strategy  $\sigma_0$  for player 0 such that :

$$\forall \sigma_{-0}, (\sigma_0, \sigma_{-0}) \in 0-NE, \text{Payoff}_0(\sigma_0, \sigma_{-0}) = 1 \text{ ?}$$

# Non Cooperative Rational Setting

## NCRS Problem

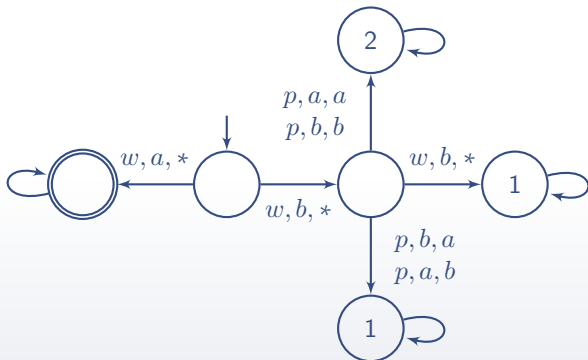
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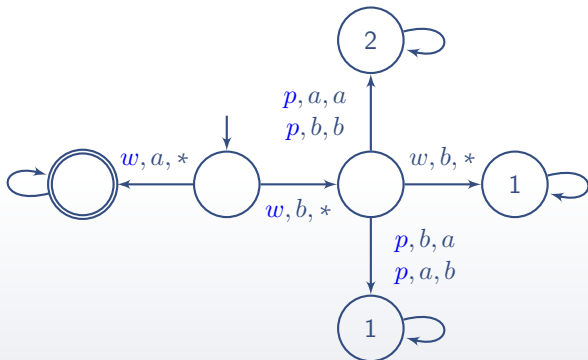
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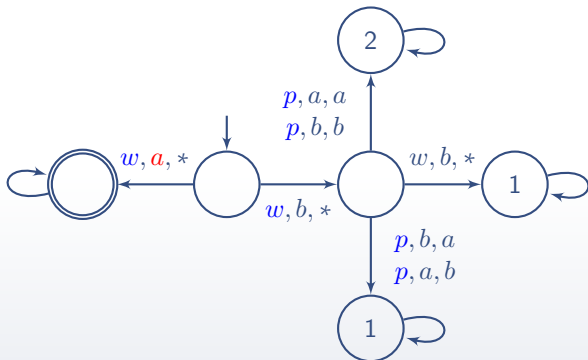
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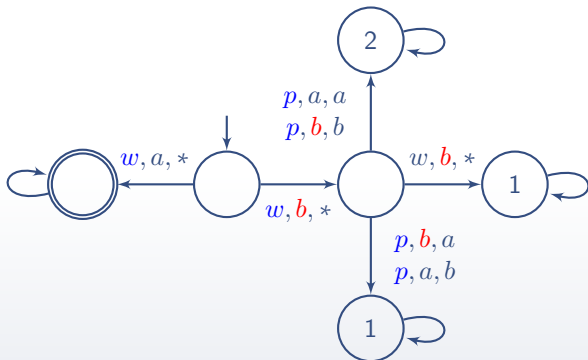
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# General Approach

## Zero-Sum game

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We design a game between two players: *Constructor* and *Spoiler* such that:

- Constructor designs a solution  $\sigma_0$  for Player 0,
- Spoiler tries to spoil  $\sigma_0$ .
  - devices a play  $\rho$  that is consistent with  $\sigma_0$  s.t.  
 $\rho \notin \phi_0$  and  $\rho \in 0 - NE$ .
- Constructor replies by designing a profitable deviation from  $\rho$  for some player  $i$ .



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## Key idea

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In each state of the zero-sum game, we keep track of :

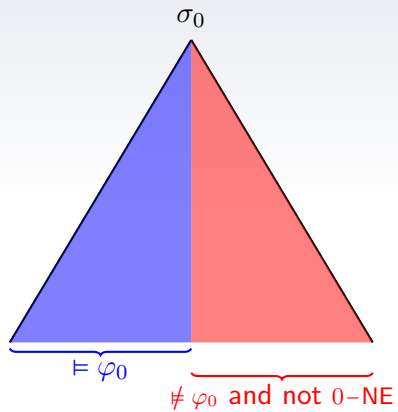
- The current state,
- The set of players that can ensure payoff 1,
- The set of players that can **unilaterally deviate**.

## The solution

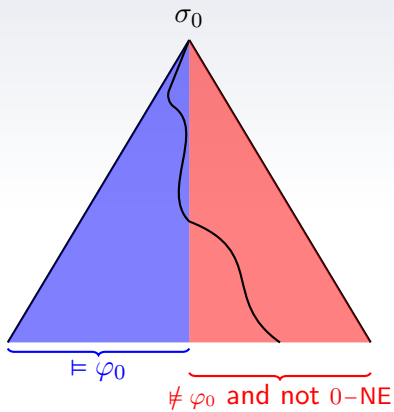
$\sigma_0$

A diagram consisting of two black lines that meet at a single point at the top, forming an inverted V-shape or a downward-pointing triangle. The apex of this triangle is labeled with the Greek letter sigma followed by a subscript zero,  $\sigma_0$ .

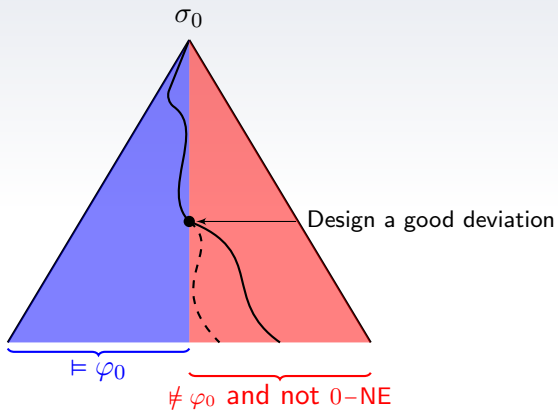
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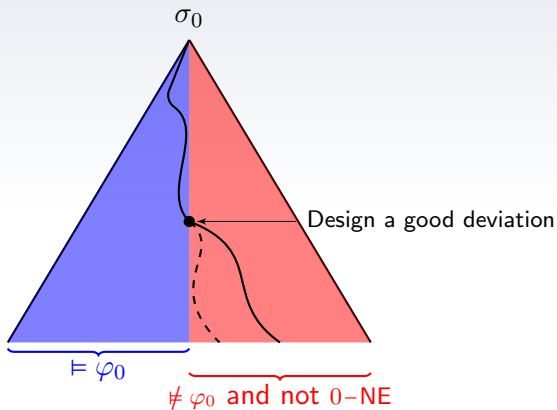
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## The solution



### Construction of a good deviation

- Choose a player  $i$  s.t.  $\text{Payoff}_i(\rho) = 0$ ,
- Pick actions for 0 that allows  $i$  to deviate,
- Pick winning actions for  $i$ .

## The zero-sum game

In each state we define two sets of players

- $D$  : Players that could deviate unilaterally,
- $W$  : Players with payoff 1.

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- $W$  : Players with payoff 1.

A play  $\rho$  is winning if

$$\rho \models \varphi_0 \text{ or } \exists i \in D \text{ s.t. Payoff}_i(\rho) = 0$$

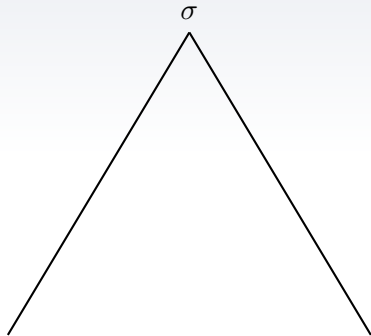
and

$$\forall j \in W, \text{Payoff}_j(\rho) = 1 \text{ .}$$



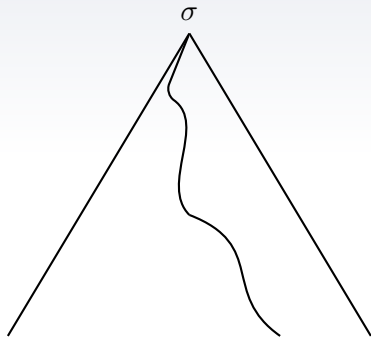
## Correctness

Let  $\sigma$  be a winning strategy for Controller.



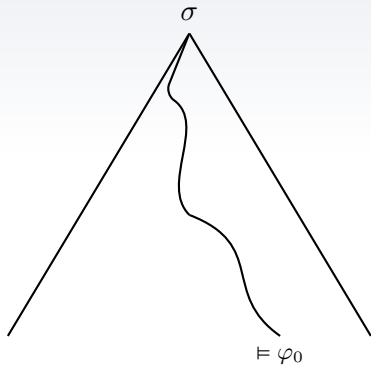
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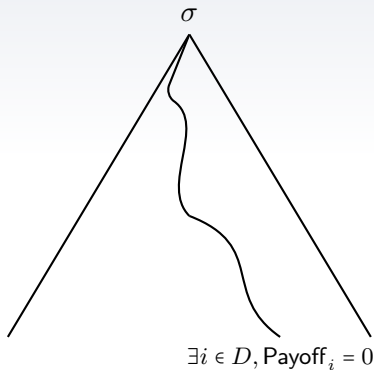
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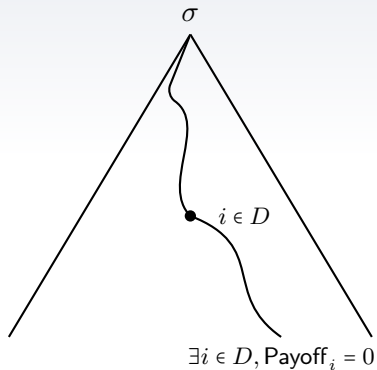
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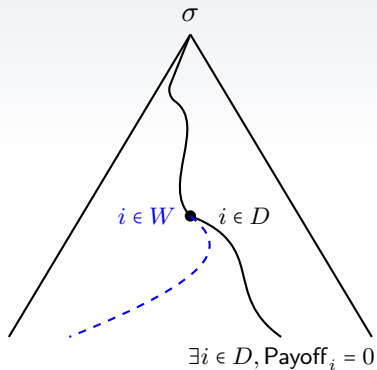
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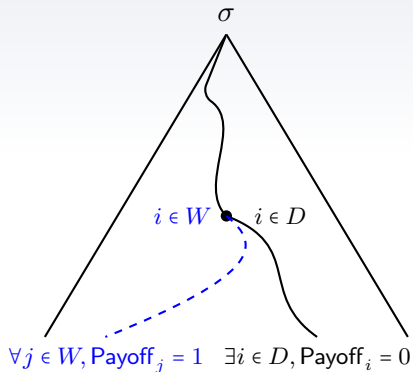
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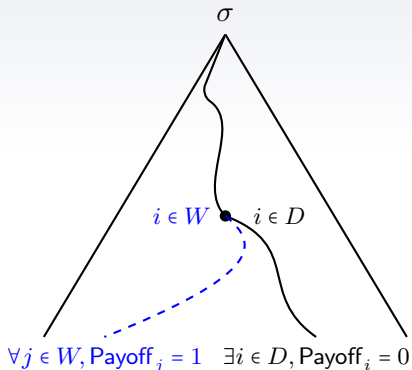
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### Remark

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- Controller chooses actions for every  $i \in W$ .



## The Negotiation Game

- 1 Constructor assigns actions for Player 0 and every player in  $W$ .
- 2 Spoiler proposes a profile for every player in  $N \setminus \{0\}$ .
- 3 Constructor can guess a deviation for a player not in  $W \cup D$ .
- 4 Spoiler has the opportunity to change the profile he proposed.

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  - ② Spoiler proposes a profile for every player in  $N \setminus \{0\}$ .
  - ③ Constructor can guess a deviation for a player not in  $W \cup D$ .
  - ④ Spoiler has the opportunity to change the profile he proposed.
- If they agree over the choices of steps 3 and 4, then we update  $W$ ,
  - If not we update  $D$ .

# Main Results

*Theorem*

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*Constructor wins iff there exists a solution for the NCRS problem.*

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## Complexity result

PERFECT INFORMATION CONCURRENT RATIONAL SYNTHESIS PROBLEM		
	Cooperative	Non-Cooperative
Safety	NP [BBMU15] NP-h [CFGR16]	<b>PSPACE</b> , PSPACE-h [CFGR16]
Reachability	NP [BBMU15] NP-h [CFGR16]	<b>PSPACE</b> , PSPACE-h [CFGR16]
Büchi	P <sub>  </sub> TIME-c [BBMU15]	<b>PSPACE</b> , PSPACE-h [CFGR16]
co-Büchi	NP [BBMU15] NP-h [CFGR16]	<b>PSPACE</b> , PSPACE-h [CFGR16]
Parity	$P_{  }^{NP}$ [BBMU15], NP-h [Umm08]	<b>EXPTIME</b> , PSPACE-h [CFGR16]
Streett	PSPACE [BBMU15], NP-h [Umm08]	<b>EXPTIME</b> , PSPACE-h [CFGR16]
Rabin	$P_{  }^{NP}$ [BBMU15], NP-h [CFGR16], coNP-h [CFGR16]	<b>EXPTIME</b> , PSPACE-h [CFGR16]
Muller	PSPACE [BBMU15], PSPACE-h [CFGR16]	<b>EXPTIME</b> , PSPACE-h [CFGR16]
LTL	2EXPTIME-C [FKL10]	2EXPTIME-C [KPV14]



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