Weakly Bounded Petri Nets

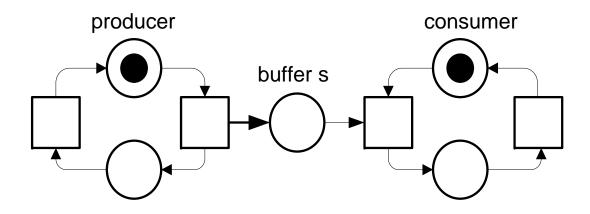
Jörg Desel

KU Eichstätt-Ingolstadt

Evry, March 5th, 2010, séminaire MeFoSyLoMa

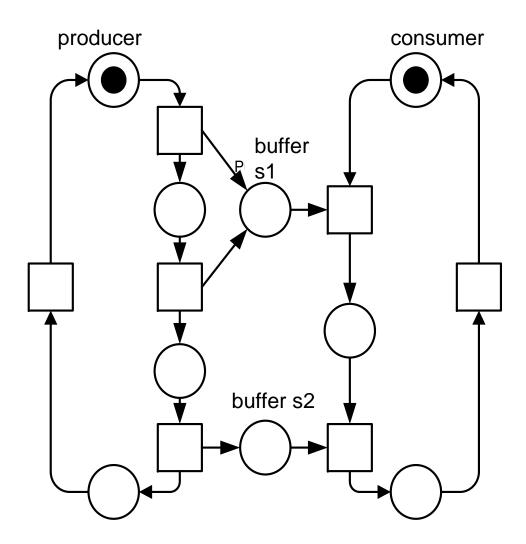
Weakly Bounded Petri Nets

Attention: Work in Progress!



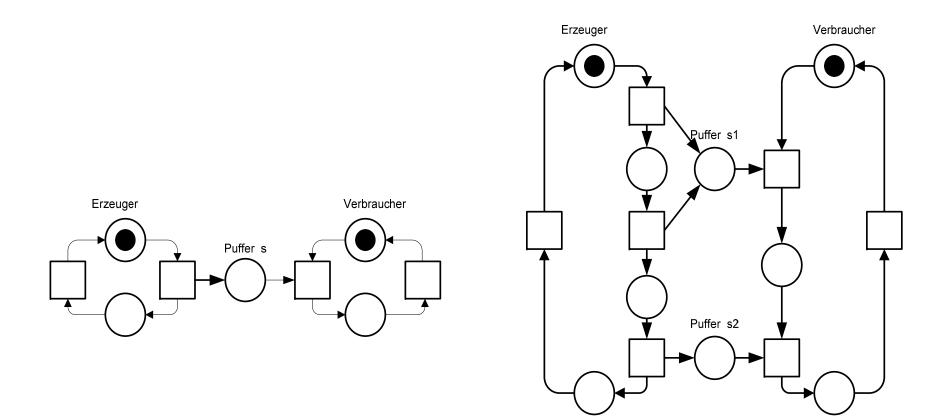
Is this Petri net bounded?

No, the place s is unbounded!



Places s1 and s2 are unbounded

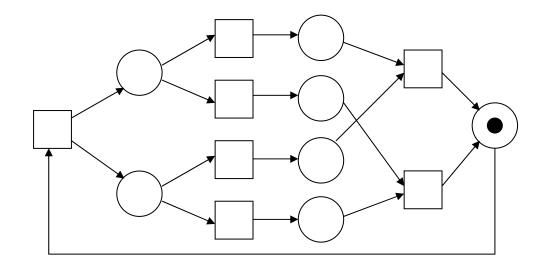
The place s1 is **"worse unbounded"**



weakly bounded

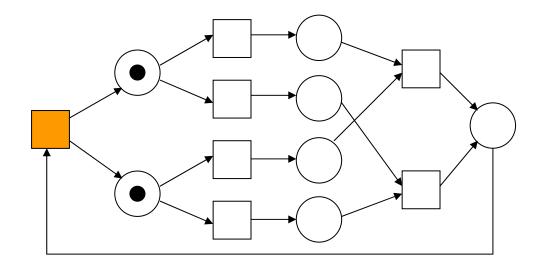
not weakly bounded

Analogy to weak liveness:



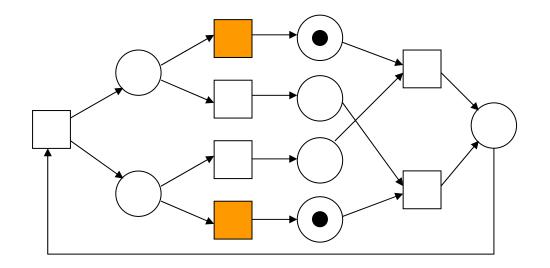
not live

Analogy to weak liveness:



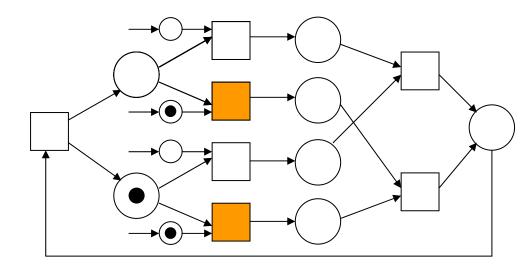
not live

Analogy to weak liveness:



not live

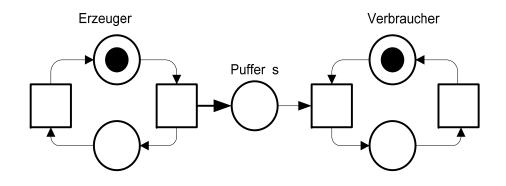
Analogy to weak liveness:



weak liveness:

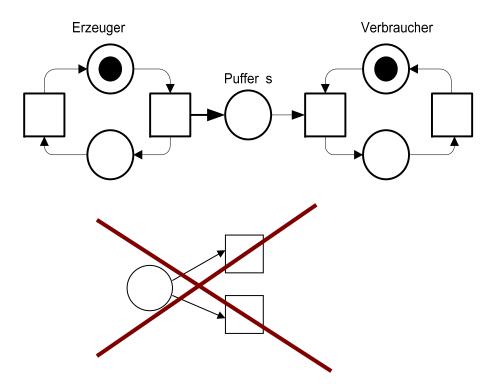
<u>choices</u> can be controlled such that the controlled net behaves lively

Analogy to weak liveness:



weak boundedness:

<u>concurrency</u> can be controlled such that the controlled net behaves boundedly



Suggestion for a definition of weak boundedness:

• We are allowed to determine the (relative) speed of the components

For each occurrence sequence, we are allowed to change the order of concurrent transitions

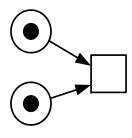
Necessary requirement:

no component is (or becomes) inactive

i.e., we assume progress (weak liveness)

Progress assumption:

If transition t is enabled then t eventually occurs



An occurrence sequence will be called **progressing**, if it satisfies the progress assumption

Definition

A place s is called **weakly k-bounded** if each progressing occurrence sequence can be permuted such that in the resulting occurrence sequence s carries never more than k tokens

A Petri net is called **weakly k-bounded** if all ist places are weakly k-bounded.

A Petri net is called weakly bounded

if each progressing occurrence sequence can be permuted such that in the resulting occurrence sequence only finitely many markings are reached

Observation

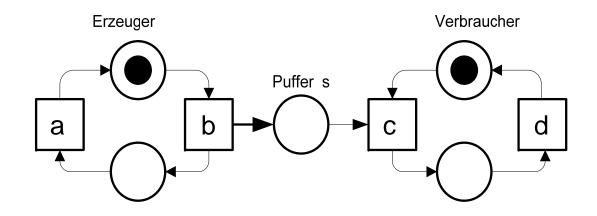
weak k-boundedness implies weak boundedness (if the set of places is finite)

weak boundedness implies weak k-boundedness for some k

This does not hold if further assumptions are made for example:

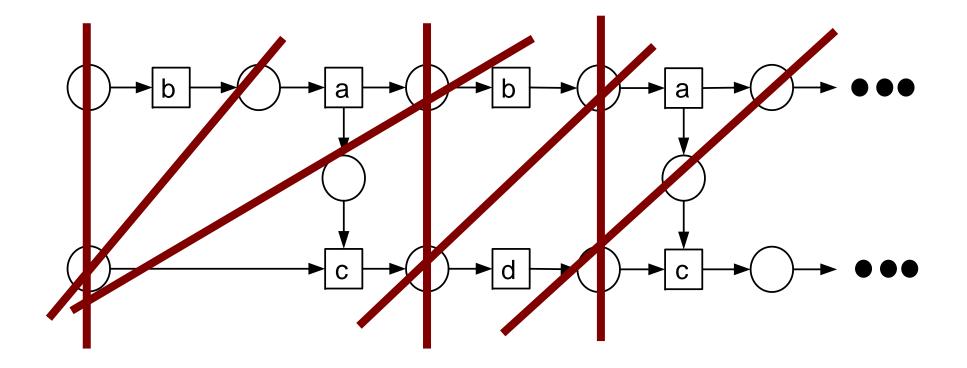
- if the consumer is generally faster than the producer (talking about the average speed)

Example

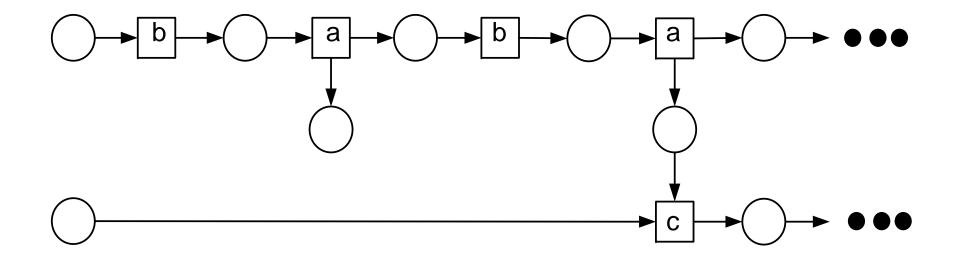


Occurrence sequence: b a b a c d b a b a c d b a b a c d ... Permutation: b a c d b a c d b a c d b a c d b a ...

Definition using partially ordered occurrence nets?





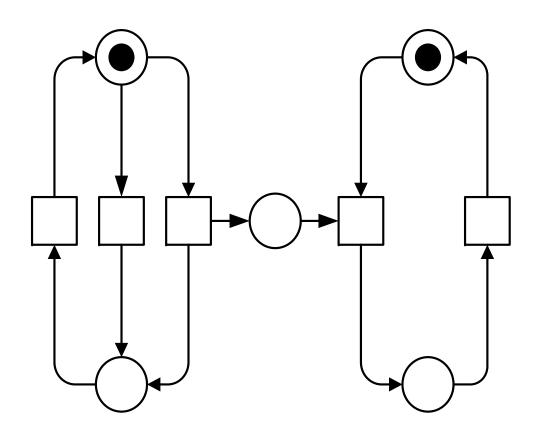


Idea (Cortadella, Kondratyev et. al.):

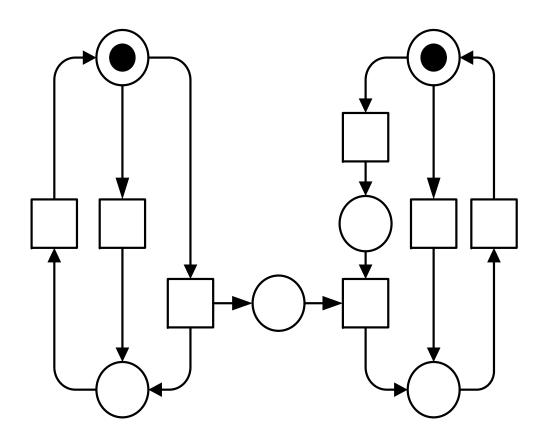
Petri nets model the control flow of concurrent programs which are executed sequentially (e.g. on one circuit)

The relative speed of the components can be controlled. Buffers are modelled by weakly bounded places.

Choices depend on (unknown) data. So choices can **not** be controlled



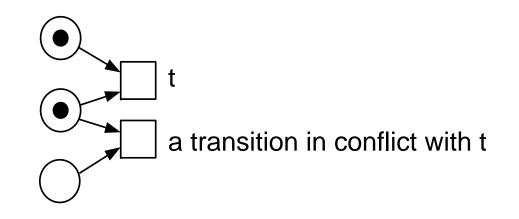
weakly bounded



weakly bounded ???

Progress assumption:

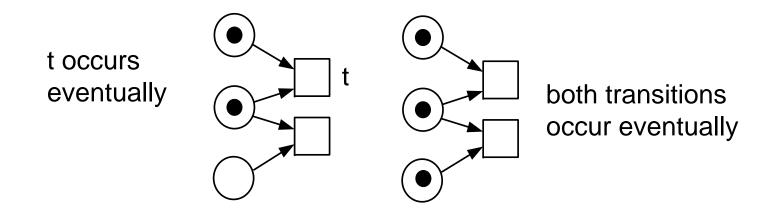
If t is enabled then either t occurs or a transition which is in conflict with t



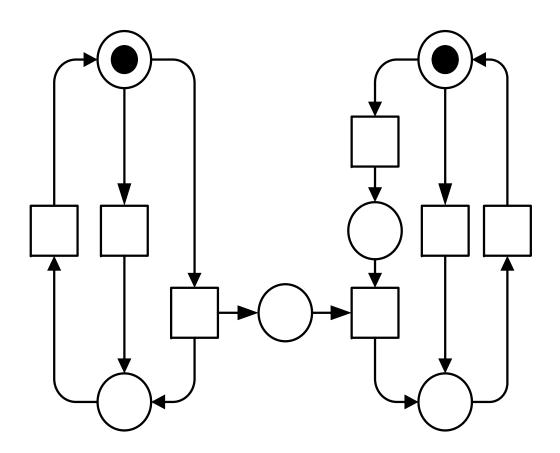
An occurrence sequence is **progressing** if it satsifies the progress assumption.

Fairness:

Each possible alternative will be selected eventually (each loop terminates ...)



An occurrence sequence is called **fair** if it satisfies the fairness assumption



weakly bounded !!!

Definition

A place s is called **weakly k-bounded**, if each progressing fair occurrence sequence can be permuted where the order of alternatives (decision of choices) is kept such that in the resulting occurrence sequence s carries never more than k tokens

A Petri net is called **weakly k-bounded** if all ist places are weakly k-bounded

A Petri net is called weakly bounded,

if each progressing fair occurrence sequence can be permuted where the order of alternatives (decision of choices) is kept such that in the resulting occurrence sequence only finitely many markings are reached

A result

restricting assumptions:

finitely many live state machines

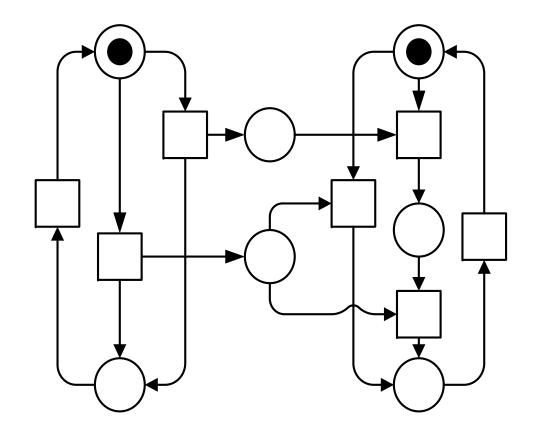
+ buffer places

a connected Petri net

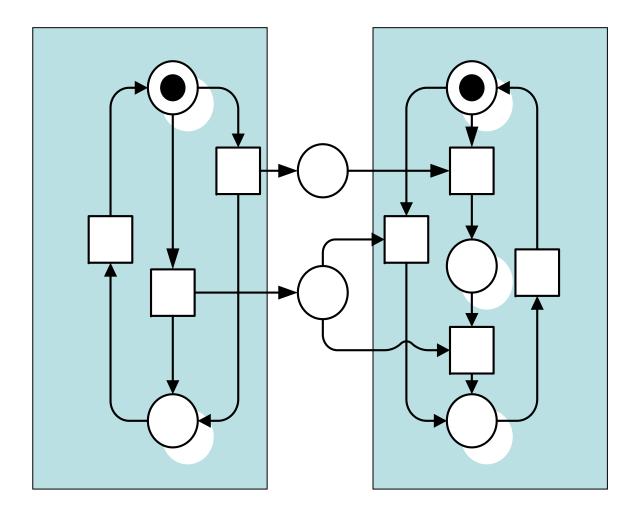
the net (composed state machines + buffers) is live

choices are either free-choice (data dependent, if-then-else) or controlled by buffer places (select statement)

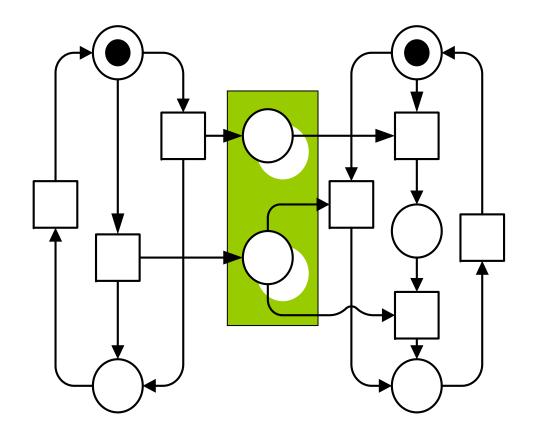
Name: coupled state machines



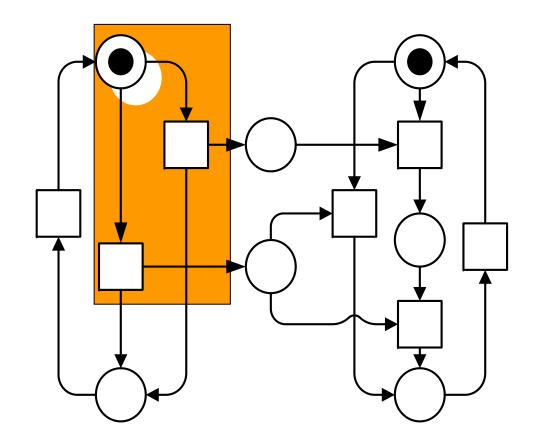
A coupled state machine



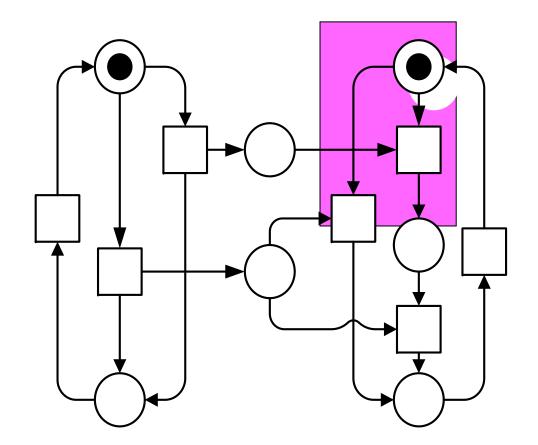
state machines



Buffer places



data dependent choice



buffer controlled choice

The Result

A coupled state machine is weakly bounded

if and only if

The rank of ist incidence matrix equals $|T| - |A \bullet| + |A| - 1$

where

T – set of transitions

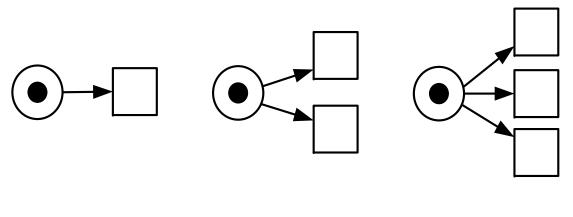
A – set of free-choice alternatives

The result

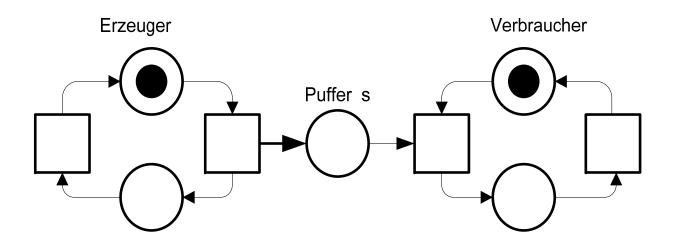
Another formulation of

The rank of ist incidence matrix equals $|T| - |A \bullet| + |A| - 1$:

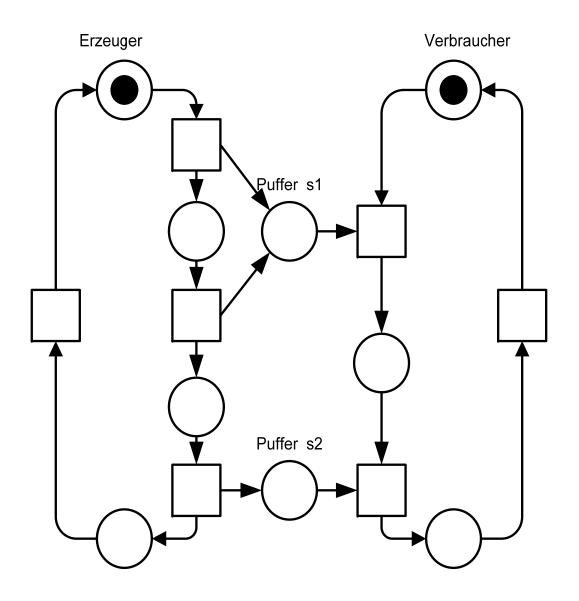
I Linearly independent T-invariants I = 1 + number of free-choice alternatives



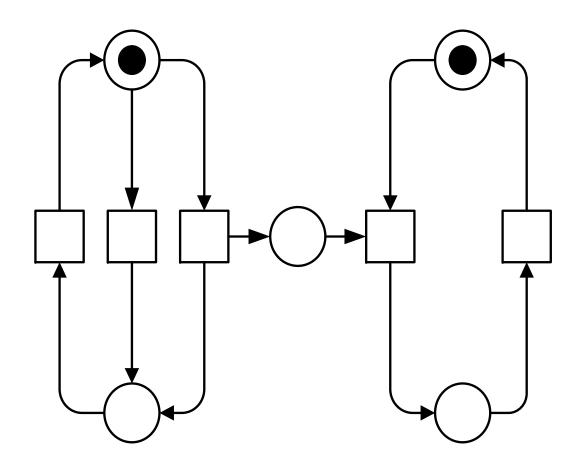
0 Alternativen 1 Alternative 2 Alternativen



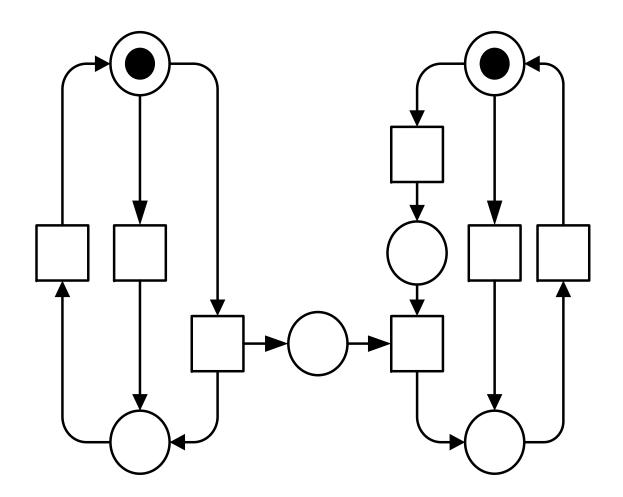
$$1 \text{ T-invariant} = 1 + 0 \text{ alternativs}$$



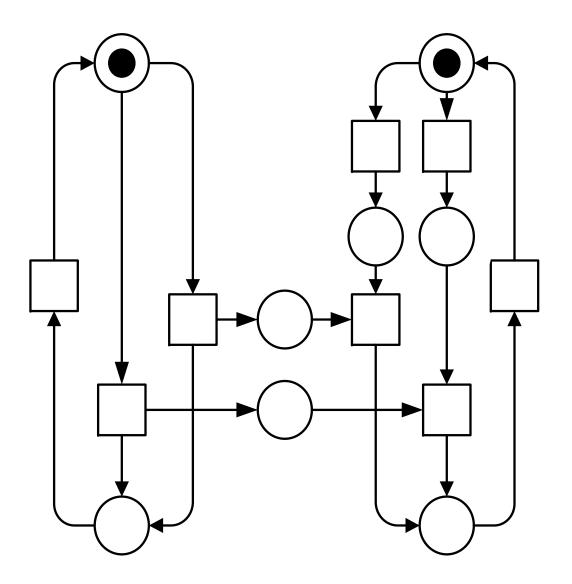
0 T-invariants \neq 1 + 0 alternativs



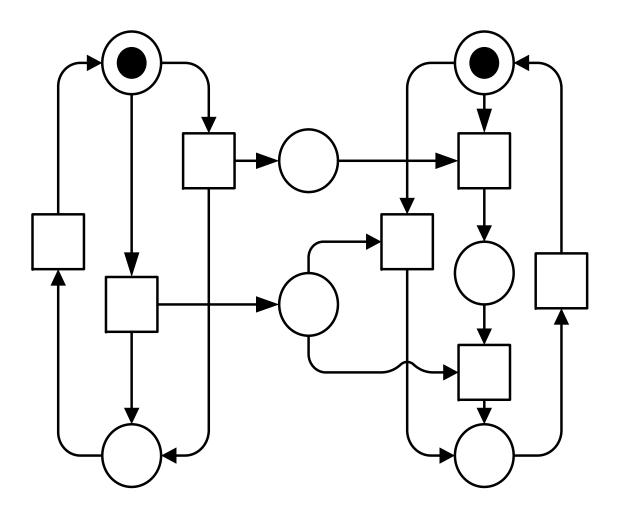
2 T-invariants = 1 + 1 alternativs



3 T-invariants = 1 + 2 alternativs



2 T-Invariants \neq 1 + 2 alternativs



2 T-invariants = 1 + 1 alternativs

This Petri net is weakly bounded but not weakly k-bounded for any k

Schedulability Analysis of Petri Nets Based on Structural Properties

Cong Liu¹, Jörg Desel², Alex Kondratyev³, Yosinori Watanabe³, Alberto Sangiovanni-Vincentelli¹

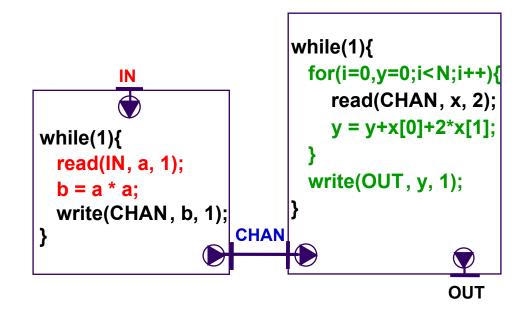
¹University of California, Berkeley, USA ²Katholische Universität Eichstätt-Ingolstadt, Germany ³Cadence Berkeley Laboratories, USA

ACSD 2006 / Fundam. Inform. 86(3): 325-341 (2008)

Scheduling Concurrent Programs

• The problem:

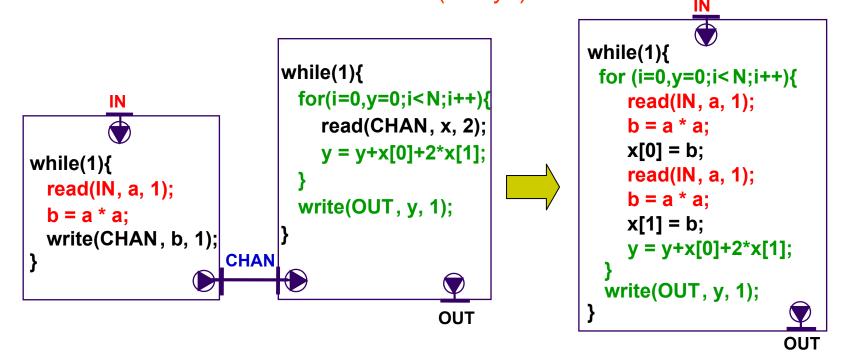
Given a set of concurrent non-terminating processes communicating through channels with infinite capacity, is there a sequential execution where channels are bounded?



Scheduling Concurrent Programs

• The problem:

Given a set of concurrent non-terminating processes communicating through channels with infinite capacity, is there a single process comprising the concurrent processes where channels are variables (arrays)?

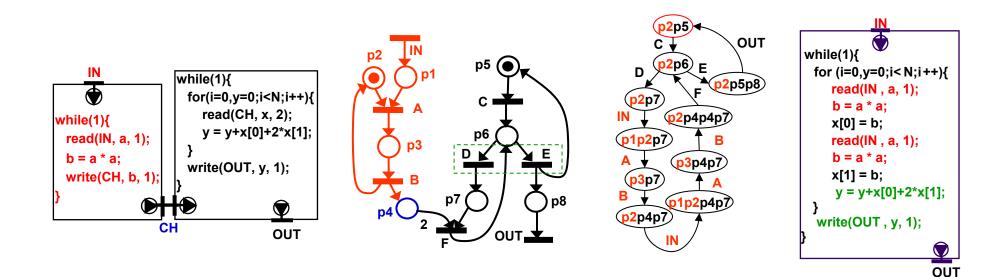


Scheduling Classification

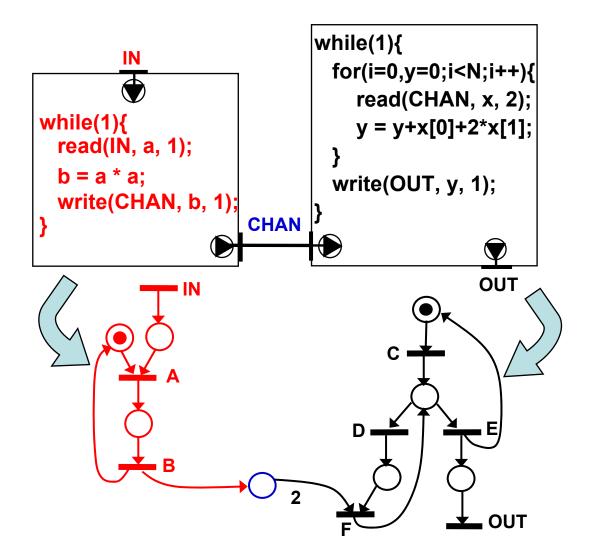
- Dynamic scheduling
 - Make all scheduling decisions at run-time
 - Context switch overhead
- Static scheduling [Lee 87]
 - Make all scheduling decisions at compile-time
 - Reduce context switch overhead
 - Restricted to specification without data-dependent controls (e.g. if-then-else)
- Quasi-static scheduling
 - Allow specification to have data-dependent controls
 - Perform static scheduling as much as possible
 - Leave data-dependent choices to be resolved at run-time

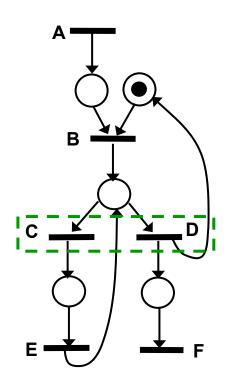
Quasi-Static Scheduling [Cortadella et al 00]

- Translate concurrent programs to a Petri net
- Find a quasi-static schedule for the Petri net
- Generate a sequential program from the schedule



Concurrent Programs → **Petri Net**



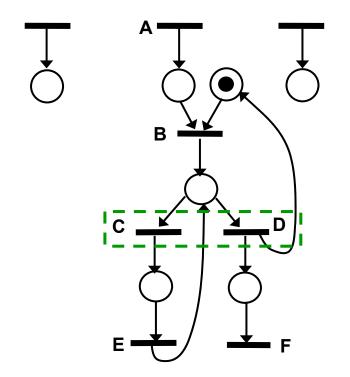


{C, D} is called a

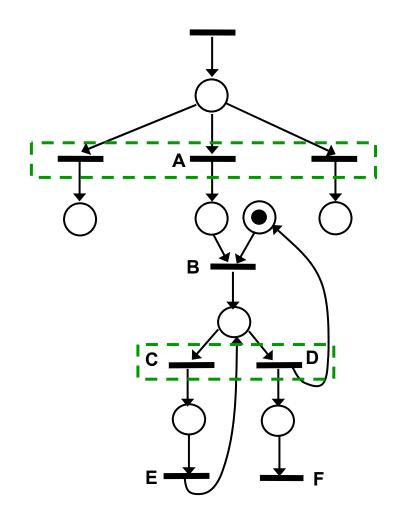
Free Choice Set (FCS).

It represents a datadependant branch (if-then-else, loop)

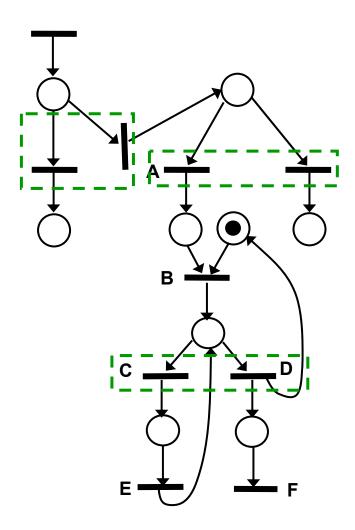
We assume that each Free Choice Set has exactly two elements



Several input transitions ? (transitions with empty pre-set)



All input transitions (transitions with empty pre-set) generate a single Free Choice Set

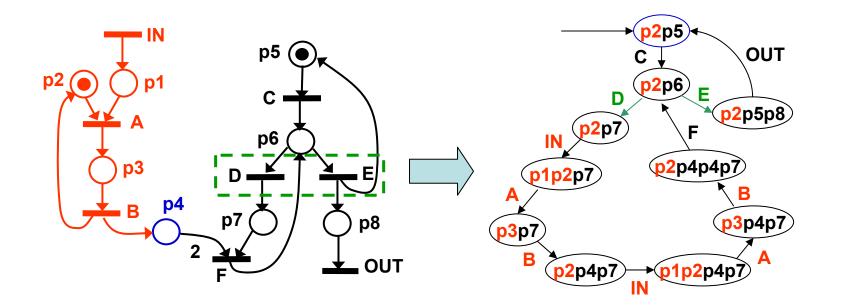


All input transitions (transitions with empty pre-set) generate a single Free Choice Set

We assume that each Free Choice Set has exactly two elements

Schedule of a Petri net

- finite directed graph with a "root"
- Vertices: mapped to markings, root to initial marking
- Edges: transition occurrences, changing the marking
- Branching vertex: corresponds to a Free Choice Set
- strongly connected



Schedulability

A Petri net is schedulable if it has a scheduleQuestion: Is a given Petri net schedulable?Is a given Petri net not schedulable?

Solution 1:Try to construct a schedule very time consuming

Solution 2: Employ necessary conditions for schedulability which are based on the Petri net structure and hence efficient to decide.

- » Checking Cyclic Dependence of Transitions using Linear Programming
- » Checking a Rank Condition using Linear Algebra

Experiments

- Codecs
 - PVRG-JPEG encoder [Hung 93]
 - Motion-JPEG encoder [Lieverse 01]
 - Philips MPEG2 decoder [Wolf 99]
 - XviD MPEG4 encoder [Broekhof 04]

	#P	#T	#Arc	#FCS	Rank	CDC	Scheduler
JPEGenc1	26	27	64	6	<0.01s	0.19s	>24hr
MJPEGenc	117	124	330	25	<0.01s	0.04s	>24hr
MPEG2dec1	116	144	358	38	<0.01s	0.25s	>24hr
MPEG4dec	72	72	184	15	<0.01s	0.16s	>24hr

Related work

Weakly bounded Message Sequence Charts

(Anca Muscholl, Blaise Genest, Dietrich Kuske)

Open Questions

Decidability for the general case (idea: exclude loops in a coverability graph

Algorithms

. . .

Further interpretations (\rightarrow Monika Heiner)

Precise relation to weakly bounded MSCs